

# DEVELOPING RESILIENT BIO-INSPIRED MODULAR ROBOTIC MINERS

 **ROBOMINERS**

## Sensors overview

Final Conference 14 November 2023  
Brussels

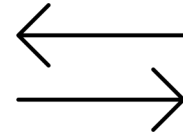
This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No. 820971.



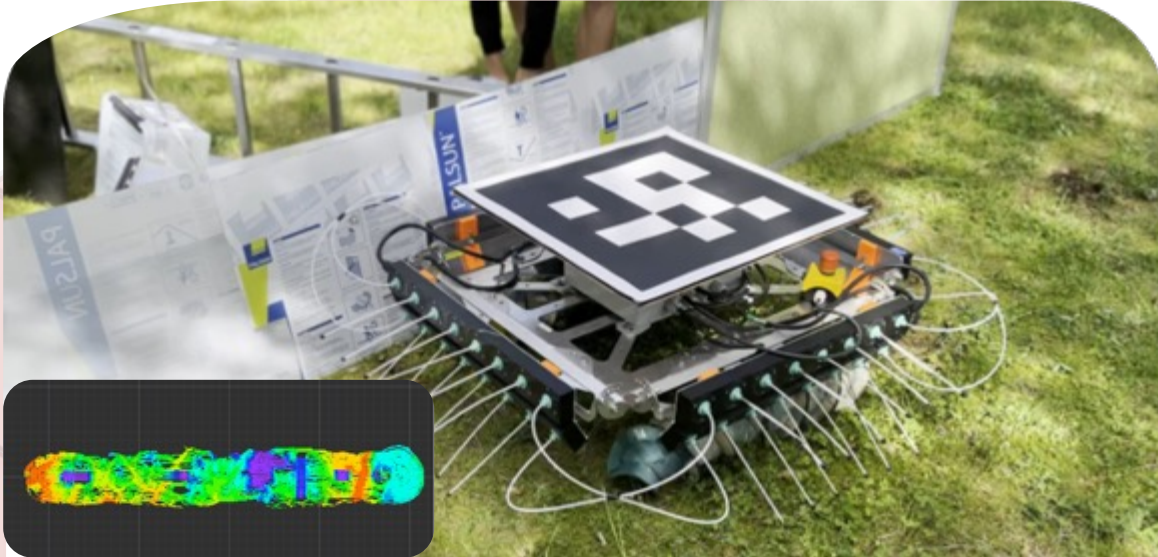
# SCENARIOS



- **Clear water, rock face visible**
- Drilling with no fluid, low pressure
- **Good ore/host rock contrast**
- Regular wall surface
- **Mined rock easily transported**  
via belt system



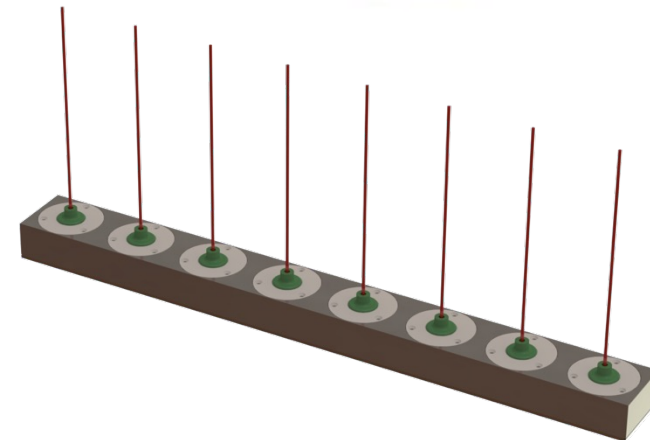
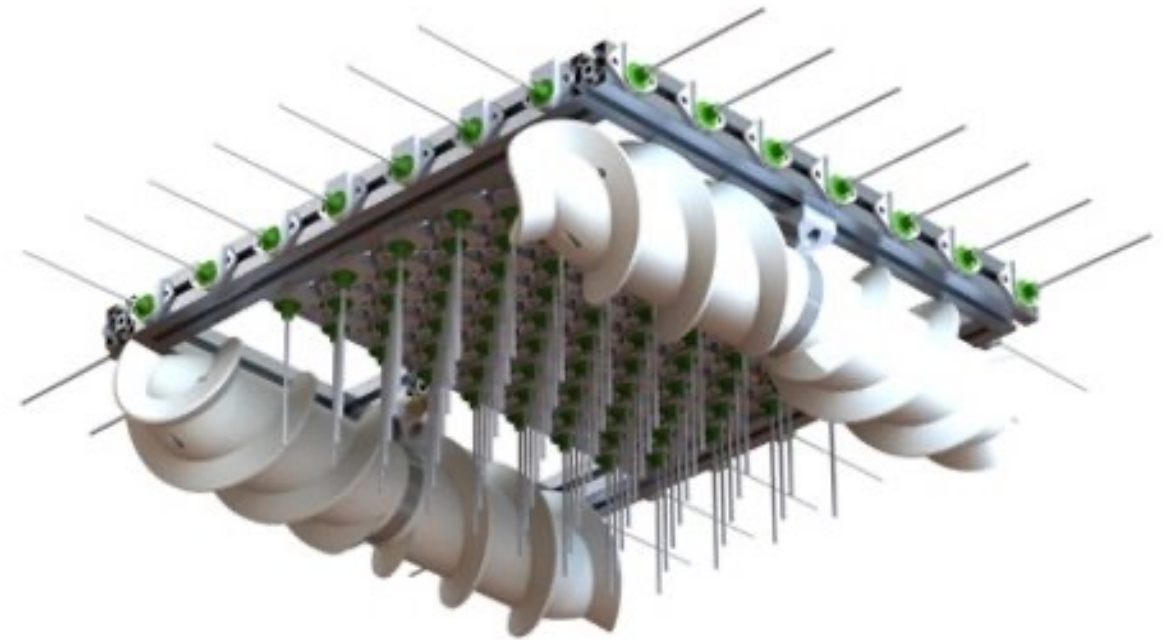
- **Opaque medium**
- Difficult physical access
- **Complex ore**
- Transport pipe with opaque, thick material
- **High pressure, debris and abrasive material**
- **Complex slurry**



### RM3 Mid-range sensor

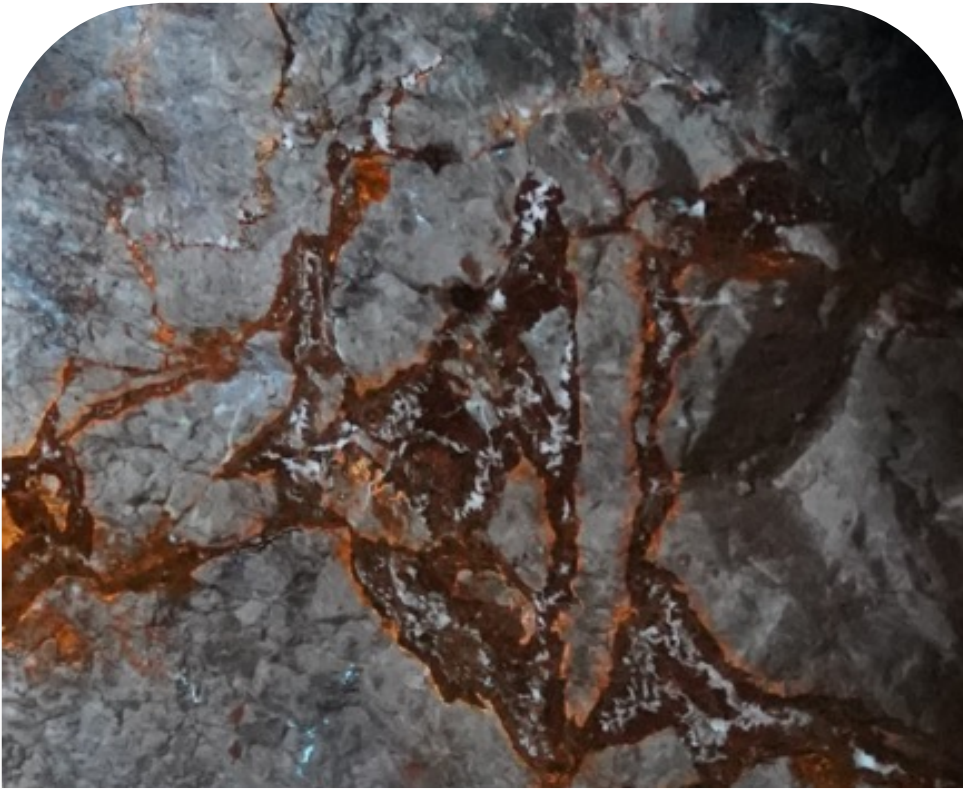
- Complementary method for visual sensors „filling the gaps“
- Challenges
  - Sensory deprivation
  - Conventional sensors do not work?
  - Few or no reliable landmarks
  - No global reference
  - Dynamic unstructured environment with poor visibility

# TACTILE MAPPING





# HYPERSPECTRAL MAPPING



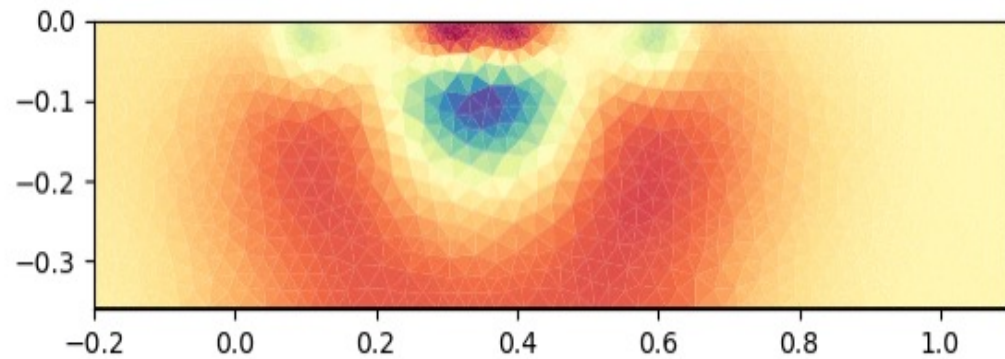
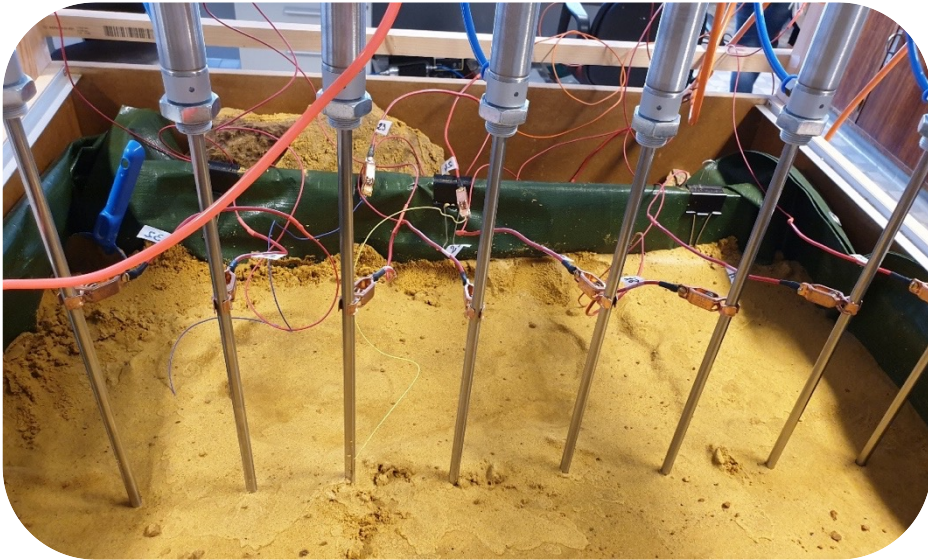
## Hyperspectral measurements

- Ultraviolet light help track Sphalerite (ZnS)
- Challenges
  - Miniaturization of hyperspectral cameras
  - Coupling of 2 cameras for extended hyperspectral range
  - Large amount of spectral information
  - Complex ore





# GEOPHYSICAL MAPPING

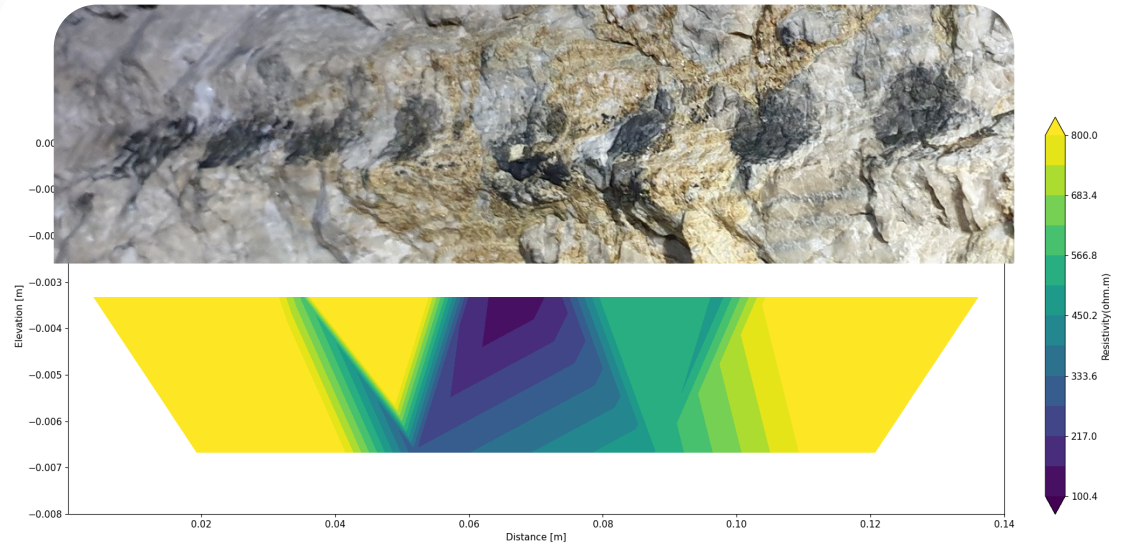


## Electric Resistivity and Induced Polarization

- Piston mounted electrodes
- Using the ore vein as medium
- Challenges
  - No rock penetration
  - Use of pressure and slurry for contact
  - Small/irregular electrode spacing



# GEOPHYSICAL MAPPING



## Electric Resistivity and Induced Polarization

- Detailed mapping for ore following
- Using the ore vein as medium
- Challenges
  - Robotic arm pressure
  - Interface with the wall mine (graphite electrodes)
  - Small electrodes spacing





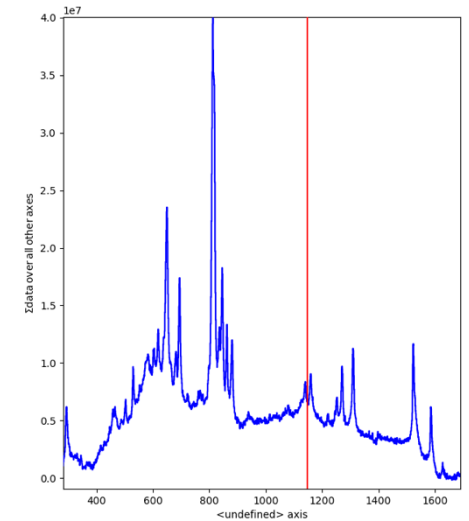
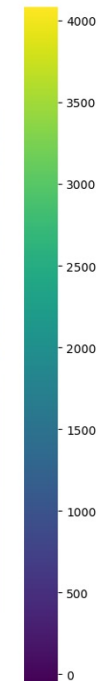
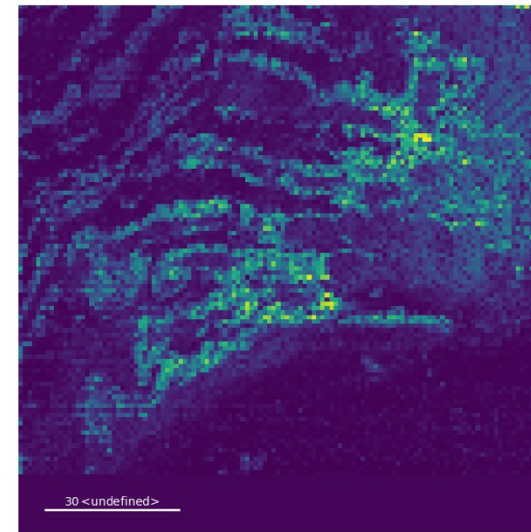
# LIBS MAPPING dry



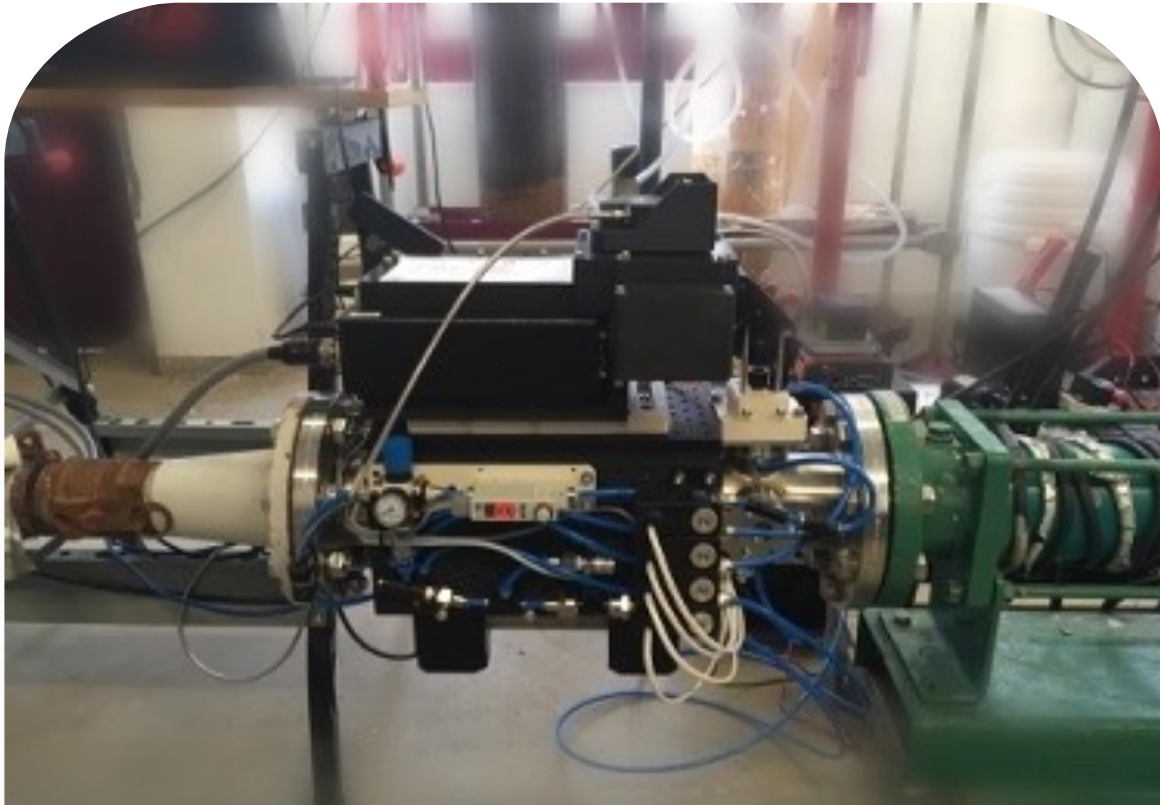
## LIBS – Laser Induced Breakdown Spectroscopy

- Mine wall chemical mapping with LIBS
- Challenges
  - Rock face visible
  - Good ore/host rock contrast
  - Irregular wall surface

(1147.)



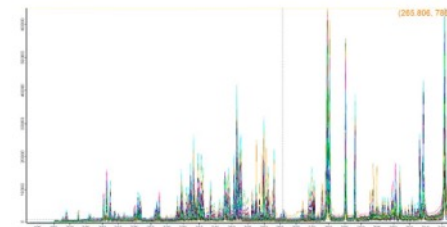
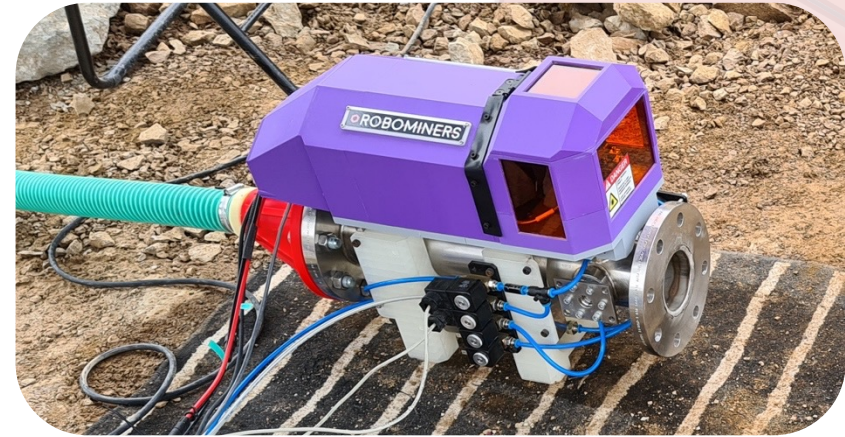




## Real-time In-slurry analysis with LIBS and SWIR

- Challenges
  - Opaque medium
  - Transport pipe with opaque, thick material
  - High pressure, debris and abrasive material
  - Complex slurry

## LIBS MAPPING wet





RM1 SENSORS



# ROBOMINERS



Geophysical probes

Locomotion system

Geophysical probes

Production tool

Slurry collection system

Reflectance sensor

Geophysical probes



LIBS slurry analysis

1 ft 1 m



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## **ROBOMINERS**

Thank you for your attention



UNIVERSIDAD POLITÉCNICA  
DE MADRID (UPM)



TAMPERE UNIVERSITY



MONTANUNIVERSITÄT  
LEOBEN (MUL)



ROYAL BELGIAN INSTITUTE  
OF NATURAL SCIENCES  
(RBINS)



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